6ES7512-1SM03-0AB0

## **Data sheet**



SIMATIC DP, CPU 1512SP F-1 PN for ET 200SP, central processing unit with 600 KB work memory for program and 2 MB for data, 1st interface: PROFINET IRT with 3-port switch, 6 ns bit performance, SIMATIC Memory Card required, BusAdapter required for port 1 and 2

General information	
Product type designation	CPU 1512SP F-1 PN
HW functional status	FS04
Firmware version	V4.0
FW update possible	Yes
Product function	
● I&M data	Yes; I&M0 to I&M3
<ul> <li>Module swapping during operation (hot swapping)</li> </ul>	Yes; Multi-hot swapping
<ul> <li>Isochronous mode</li> </ul>	Yes; only with PROFINET; with minimum OB $6x$ cycle of $500~\mu s$
SysLog	Yes
Engineering with	
STEP 7 TIA Portal configurable/integrated from version	V20 (FW V4.0) / V18 (FW V3.0) or higher; configurable with older TIA Portal versions as 6ES7 512-1SK01-0AB0
Configuration control	
via dataset	Yes
Control elements	
Mode selector switch	1
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
Mains/voltage failure stored energy time	10 ms
Input current	
Current consumption (rated value)	0.48 A
Current consumption, max.	0.7 A
Inrush current, max.	1.34 A; Rated value
l²t	0.3 A <sup>2</sup> ·s
Power	
Infeed power to the backplane bus	8.05 W
Power loss	
Power loss, typ.	3.5 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
• integrated (for program)	600 kbyte
• integrated (for data)	2 Mbyte
Load memory	

<ul> <li>Plug-in (SIMATIC Memory Card), max.</li> </ul>	32 Gbyte
Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	6 ns
for word operations, typ.	7 ns
for fixed point arithmetic, typ.	9 ns
for floating point arithmetic, typ.	37 ns
CPU-blocks	
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the user: 1
0:	59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	2 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB A Number range	0 65 525
Number range     Size may	0 65 535 600 kbyte
• Size, max.	600 kbyte
Number range	0 65 535
• Size, max.	600 kbyte
OB	ood ruyte
• Size, max.	600 kbyte
Number of free cycle OBs	100
Number of time alarm OBs	20
Number of delay alarm OBs	20
Number of cyclic interrupt OBs	20; With minimum OB 3x cycle of 250 μs
Number of process alarm OBs	50
Number of DPV1 alarm OBs	3
Number of isochronous mode OBs	1
Number of isocirionous mode OBs     Number of technology synchronous alarm OBs	2
Number of startup OBs	100
Number of startup OBs     Number of asynchronous error OBs	4
Number of synchronous error OBs	2
Number of diagnostic alarm OBs	1
Nesting depth	
per priority class	24; Up to 8 possible for F-blocks
Counters, timers and their retentivity	2-1, Op to a possible for 1 blooks
S7 counter	
• Number	2 048
Retentivity	2010
— adjustable	Yes
IEC counter	
Number	Any (only limited by the main memory)
Retentivity	, , , , , , , , , , , , , , , , , , , ,
— adjustable	Yes
S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	256 kbyte; in total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 216 KB
Flag	
• Size, max.	16 kbyte
<ul> <li>Number of clock memories</li> </ul>	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
Retentivity adjustable	Yes

Retentivity preset	No
Local data	110
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	or reste, max. To the por block
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	2 0 10, max. name of moduloc / casmoduloc
• Inputs	32 kbyte; All inputs are in the process image
• Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	oz najvoj. ni oznjeno dre ni dre procese miage
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
Number of subprocess images, max.	32
Address space per module	
Address space per module, max.	288 byte; For input and output data respectively
Address space per station	
Address space per station, max.	2 560 byte; for central inputs and outputs; depending on configuration; 2 048 bytes for ET 200SP modules + 512 bytes for ET 200AL modules
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	1
Number of IO Controllers	
• integrated	1
• Via CM	0
Rack	
Modules per rack, max.	82; CPU + 64 modules + server module (mounting width max. 1 m) + 16 ET 200AL modules
<ul> <li>Quantity of operable ET 200SP modules, max.</li> </ul>	64
<ul> <li>Quantity of operable ET 200AL modules, max.</li> </ul>	16
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
• supported	Yes
● to DP, master	Yes; Via CM DP module
• on DP, device	Yes; Via CM DP module
● in AS, master	
	Yes
• in AS, device	Yes
• on Ethernet via NTP	
on Ethernet via NTP     Interfaces	Yes Yes
on Ethernet via NTP  Interfaces  Number of PROFINET interfaces	Yes Yes
on Ethernet via NTP  Interfaces  Number of PROFINET interfaces  Number of PROFIBUS interfaces	Yes Yes 1 1; Via CM DP module
on Ethernet via NTP  Interfaces  Number of PROFINET interfaces  Number of PROFIBUS interfaces  Optical interface	Yes Yes
on Ethernet via NTP  Interfaces  Number of PROFINET interfaces  Number of PROFIBUS interfaces	Yes Yes 1 1; Via CM DP module
on Ethernet via NTP  Interfaces  Number of PROFINET interfaces  Number of PROFIBUS interfaces  Optical interface	Yes Yes 1 1; Via CM DP module
on Ethernet via NTP  Interfaces  Number of PROFINET interfaces  Number of PROFIBUS interfaces  Optical interface  1. Interface  Interface types  RJ 45 (Ethernet)	Yes Yes  1 1; Via CM DP module Yes; Via SIMATIC BusAdapter  Yes; X1 P3; opt. X1 P1 and X1 P2 via BusAdapter BA 2x RJ45
● on Ethernet via NTP  Interfaces  Number of PROFINET interfaces  Number of PROFIBUS interfaces  Optical interface  1. Interface  Interface types	Yes Yes  1 1; Via CM DP module Yes; Via SIMATIC BusAdapter

BusAdapter (PROFINET)	Yes; compatible BusAdapters: BA 2x RJ45, BA 2x M12, BA 2x FC, BA 2x LC, BA LC/RJ45, BA LC/FC, BA 2x SCRJ, BA SCRJ/RJ45, BA SCRJ/FC	
Protocols	5.1.201.0.10, 5.1.201.0, 5.1.201.0.10	
IP protocol	Yes; IPv4	
PROFINET IO Controller	Yes	
PROFINET IO Device	Yes	
SIMATIC communication	Yes	
Open IE communication	Yes; Optionally also encrypted	
Web server	Yes	
Media redundancy	Yes	
PROFINET IO Controller		
Services		
— Isochronous mode	Yes	
— Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)	
— IRT	Yes	
— PROFlenergy	Yes; per user program	
Prioritized startup	Yes; Max. 32 PROFINET devices	
— Number of connectable IO Devices, max.	128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET	
<ul> <li>Of which IO devices with IRT, max.</li> </ul>	64	
<ul> <li>Number of connectable IO Devices for RT, max.</li> </ul>	128	
— of which in line, max.	128	
<ul> <li>Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8; in total across all interfaces	
<ul> <li>Number of IO Devices per tool, max.</li> </ul>	8	
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data	
— PROFINET Security Class	1	
Update time for IRT		
— for send cycle of 250 μs	$250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of $500~\mu s$ of the isochronous OB is decisive	
— for send cycle of 500 μs	500 μs to 8 ms	
— for send cycle of 1 ms	1 ms to 16 ms	
<ul><li>for send cycle of 2 ms</li></ul>	2 ms to 32 ms	
— for send cycle of 4 ms	4 ms to 64 ms	
— With IRT and parameterization of "odd" send cycles	Update time = set "odd" send clock (any multiple of 125 $\mu s:375~\mu s,625~\mu s \dots 3~875~\mu s)$	
Update time for RT		
— for send cycle of 250 μs	250 μs to 128 ms	
— for send cycle of 500 μs	500 μs to 256 ms	
— for send cycle of 1 ms	1 ms to 512 ms	
— for send cycle of 2 ms	2 ms to 512 ms	
— for send cycle of 4 ms	4 ms to 512 ms	
PROFINET IO Device		
Services		
— Isochronous mode	No	
— IRT	Yes	
— PROFlenergy	Yes; per user program	
— Shared device	Yes	
<ul> <li>Number of IO Controllers with shared device, max.</li> </ul>	4	
<ul> <li>activation/deactivation of I-devices</li> </ul>	Yes; per user program	
<ul> <li>Asset management record</li> </ul>	Yes; per user program	
— PROFINET Security Class	SNMP Configuration and DCP Read Only	
2. Interface		
Interface types		
• RS 485	Yes; Via CM DP module	
Number of ports	1	
Protocols		
PROFIBUS DP master	Yes	
PROFIBUS DP device	Yes	
SIMATIC communication	Yes	

<ul> <li>Number of connections, max.</li> </ul>	48; Of which 4 each reserved for ES and HMI
<ul> <li>max. number of DP devices</li> </ul>	125; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
Services	PROFIBOS OF PROFINET
	No
Equidistance      Isochronous mode	No
activation/deactivation of DP devices	Yes
Interface types	TES
RJ 45 (Ethernet)	Yes
<ul><li>100 Mbps</li><li>Autonegotiation</li></ul>	Yes
<u> </u>	Yes
<ul> <li>Autocrossing</li> <li>Industrial Ethernet status LED</li> </ul>	Yes
RS 485	165
• Transmission rate, max.	12 Mbit/s
Protocols	12 IVIDIUS
PROFIsafe	Voc. \/2.4 / \/2.6
	Yes; V2.4 / V2.6
Number of connections  Number of connections, max.	128: via integrated interfaces of the CDLL and connected CDs / CMs
Number of connections, max.     Number of connections reserved for ES/HMI/web	128; via integrated interfaces of the CPU and connected CPs / CMs 10
Number of connections via integrated interfaces	88
<ul> <li>Number of connections via integrated interfaces</li> <li>Number of connections per CP/CM</li> </ul>	32
· · · · · · · · · · · · · · · · · · ·	32 16
Number of S7 routing paths  Redundancy mode	10
Redundancy mode  • H-Sync forwarding	Yes
Media redundancy	165
Media redundancy	Yes; only via BusAdapter
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager;
IVII VI	MRP Client
<ul> <li>MRP interconnection, supported</li> </ul>	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
<ul> <li>Switchover time on line break, typ.</li> </ul>	200 ms; For MRP, bumpless for MRPD
<ul> <li>Number of stations in the ring, max.</li> </ul>	50
SIMATIC communication	
<ul> <li>PG/OP communication</li> </ul>	Yes; encryption with TLS V1.3 pre-selected
• S7 routing	Yes
<ul> <li>Data record routing</li> </ul>	Yes
<ul> <li>S7 communication, as server</li> </ul>	Yes
<ul> <li>S7 communication, as client</li> </ul>	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
<ul> <li>several passive connections per port, supported</li> </ul>	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; max. 78 multicast circuits
• DHCP	Yes
• DNS	Yes
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
• web API	
<ul><li>Number of sessions, max.</li></ul>	50
<ul> <li>number of simultaneous HTTP calls, max.</li> </ul>	4

— HTTP request body, max.	131 072 byte
OPC UA	101 012 byte
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes; Data Access (registered Read/Write), Method Call
Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
<ul> <li>Number of connections, max.</li> </ul>	4
<ul> <li>Number of nodes of the client interfaces, recommended max.</li> </ul>	1 000
<ul> <li>Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/OPC_I max.</li> </ul>	300
<ul> <li>Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max.</li> </ul>	20
<ul> <li>Number of elements for one call of OPC_UA_MethodGetHandleList, max.</li> </ul>	100
<ul> <li>Number of simultaneous calls of the client instructions for session management, per connection, max.</li> </ul>	1
<ul> <li>Number of simultaneous calls of the client instructions for data access, per connection, max.</li> </ul>	5
<ul> <li>Number of registerable nodes, max.</li> </ul>	5 000
<ul> <li>Number of registerable method calls of OPC_UA_MethodCall, max.</li> </ul>	100
<ul> <li>Number of inputs/outputs when calling OPC_UA_MethodCall, max.</li> </ul>	20
OPC UA Server	Yes; data access (read, write, subscribe), method call, alarms & condition (A&C), custom address space, role-based access control
<ul> <li>Application authentication</li> </ul>	Yes
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss
<ul><li>User authentication</li></ul>	"anonymous" or by user name & password
<ul> <li>— GDS support (certificate management)</li> </ul>	Yes
<ul><li>Number of sessions, max.</li></ul>	32
<ul> <li>Number of accessible variables, max.</li> </ul>	50 000
Number of registerable nodes, max.	10 000
<ul> <li>Number of subscriptions per session, max.</li> </ul>	50
— Sampling interval, min.	100 ms
<ul><li>— Publishing interval, min.</li></ul>	200 ms
— Number of server methods, max.	20; max. 20 concurrently running jobs each for asynchronous instructions OPC_UA_ServerMethodPre and OPC_UA_ServerMethodPost
Number of inputs/outputs per server method, max.	4 000 for 4 a compling interval and 4 a conditions
Number of monitored items, recommended max.	4 000; for 1 s sampling interval and 1 s send interval
Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
Number of nodes for user-defined server interfaces, max.  Alarms and Conditions	15 000 Yes
Alarms and Conditions     Number of program clarms	Yes
Number of program alarms	100
Number of alarms for system diagnostics  Further protocols	50
Further protocols	Voc. MODBLIS TOD
MODBUS  S7 massage functions	Yes; MODBUS TCP
S7 message functions  Number of login stations for message functions, may	32
Number of login stations for message functions, max.	32 250
number of tags/attributes for subscriptions, max	2 000
number of tags/attributes for subscriptions, max.	Yes
Program alarms  Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	5 000
Number of ioadable program messages in Non, max.  Number of simultaneously active program alarms	
Number of program alarms	600
Number of alarms for system diagnostics	100
<ul> <li>Number of alarms for motion technology objects</li> </ul>	160

Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	Yes
Number of breakpoints	8
Profiling	Yes
Status/control	
Status/control variable	Yes; without fail-safe
• Variables	inputs/outputs, bit memories, DBs, peripheral I/Os (without fail-safe), times, counters
<ul> <li>Number of variables, max.</li> </ul>	
<ul><li>of which status variables, max.</li></ul>	200; per job
<ul><li>of which control variables, max.</li></ul>	200; per job
Forcing	
<ul><li>Forcing</li></ul>	Yes; without fail-safe
Forcing, variables	peripheral inputs/outputs (without fail-safe)
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
Number of entries, max.	1 000
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4
Memory size per trace, max.	512 kbyte
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
Monitoring of the supply voltage (PWR-LED)	Yes
Connection display LINK TX/RX	Yes
• Connection display Link 17/KA	165
Supported technology objects	
	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Supported technology objects	Yes; Note: The number of technology objects affects the cycle time of the PLC
Supported technology objects  Motion Control  • Number of available Motion Control resources for	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Supported technology objects  Motion Control  Number of available Motion Control resources for technology objects	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Supported technology objects  Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120
Supported technology objects  Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120
Supported technology objects  Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120 40 80
Supported technology objects  Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120 40 80 160
Supported technology objects  Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80
Motion Control  Number of available Motion Control resources for technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20
Motion Control  Number of available Motion Control resources for technology objects  Required Motion Control resources  per speed-controlled axis  per positioning axis  per synchronous axis  per external encoder  per output cam  per cam track	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160
Motion Control  Number of available Motion Control resources for technology objects  Required Motion Control resources  per speed-controlled axis  per positioning axis  per synchronous axis  per external encoder  per output cam  per cam track  per probe  Positioning axis  Number of positioning axes at motion control cycle	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160 40
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160 40
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160 40
Motion Control  Number of available Motion Control resources for technology objects  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per external encoder  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160 40 11
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160 40 11 14  Yes; Universal PID controller with integrated optimization
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_Step	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160 40  11 14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_3Step PID-Temp	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160 40  11 14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_3Step PID-Temp  Counting and measuring High-speed counter	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160 40  11 14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_3Step PID-Temp  Counting and measuring High-speed counter	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160 40  11 14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller PID_Compact PID_3Step PID-Temp  Counting and measuring High-speed counter  Standards, approvals, certificates	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 1 120  40 80 160 80 20 160 40  11 14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_3Step PID-Temp  Counting and measuring High-speed counter  Standards, approvals, certificates  Ecological footprint	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  1 120  40  80  160  80  20  160  40  11  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_3Step PID-Temp  Counting and measuring High-speed counter  Standards, approvals, certificates  Ecological footprint  environmental product declaration	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  1 120  40  80  160  80  20  160  40  11  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes
Motion Control  Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller PID_Compact PID_3Step PID-Temp Counting and measuring High-speed counter  Standards, approvals, certificates  Ecological footprint environmental product declaration Global warming potential	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool  1 120  40 80 160 80 20 160 40  11  14  Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Yes  Yes

— global warming potential, (during operation) [CO2	61.8 kg		
eq] — global warming potential, (after end of life cycle)	-0.949 kg		
[CO2 eq]			
Highest safety class achievable in safety mode			
Performance level according to ISO 13849-1	PLe		
SIL acc. to IEC 61508	SIL 3		
Probability of failure (for service life of 20 years and repair time	·		
<ul> <li>Low demand mode: PFDavg in accordance with SIL3</li> </ul>	< 2.00E-05		
High demand/continuous mode: PFH in accordance with SIL3	< 1.00E-09		
product functions / security / header			
PROFINET Security Class	1		
signed firmware update	Yes		
Secure Boot	Yes		
safely removing data	Yes		
Ambient conditions			
Ambient temperature during operation			
horizontal installation, min.	-30 °C; No condensation		
horizontal installation, max.	60 °C		
vertical installation, min.	-30 °C; No condensation		
vertical installation, max.	50 °C		
Altitude during operation relating to sea level			
Installation altitude above sea level, max.	5 000 m; Restrictions for installa	ation altitudes > 2 000 m	see manual
configuration / header	3 000 III, Restrictions for installe	ation attitudes > 2 000 m,	SCC manual
configuration / programming / header			
Programming language	Variable fallers		
— LAD	Yes; incl. failsafe		
— FBD	Yes; incl. failsafe		
— STL	Yes		
— SCL	Yes		
— CFC	No		
— GRAPH	Yes		
Know-how protection			
<ul> <li>User program protection/password protection</li> </ul>	Yes		
Copy protection	Yes		
Block protection	Yes		
Access protection			
<ul> <li>protection of confidential configuration data</li> </ul>	Yes		
<ul> <li>Protection level: Write protection</li> </ul>	Yes		
<ul> <li>Protection level: Read/write protection</li> </ul>	Yes		
<ul> <li>Protection level: Write protection for Failsafe</li> </ul>	Yes		
<ul> <li>Protection level: Complete protection</li> </ul>	Yes		
User administration	Yes; device-wide and centralize	ed	
Number of users	100		
Number of groups	100		
Number of roles	50		
programming / cycle time monitoring / header			
• lower limit	adjustable minimum cycle time		
upper limit	adjustable maximum cycle time		
Dimensions	, 2) 3.2 4.1110		
Width	100 mm		
Height	117 mm		
· ·			
·	Depth 75 mm		
Weights	205 ~		
Weight, approx.	265 g		
Classifications			
		Version	Classification
	eClass	14	27-24-26-07
	eClass	12	27-24-26-07

eClass	9.1	27-24-26-07
eClass	9	27-24-26-07
eClass	8	27-24-26-07
eClass	7.1	27-24-26-07
eClass	6	27-24-26-07
ETIM	9	EC001603
ETIM	8	EC001603
ETIM	7	EC001603
IDEA	4	3565
UNSPSC	15	32-15-17-05

**General Product Approval** 

Manufacturer Declara-<u>tion</u>





Miscellaneous



**Miscellaneous** 

**General Product Approval** 

For use in hazardous locations

<u>KC</u>





CCC-Ex

<u>FM</u>



For use in hazardous locations

**Functional Saftey** 

Marine / Shipping



CCC-Ex

**Miscellaneous** 



Type Examination Certificate



Marine / Shipping







NK / Nippon Kaiji Ky-okai





Marine / Shipping

other

Environment

CCS (China Classification Society)



88080

**PROFINET** 



last modified:

12/8/2024